

ENERGY

Give It All You Got

Using big data machine learning ensembles
for condition monitoring

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Outline

- Motivating problem condition monitoring of gearbox issue detection in SCADA
- Developments around data
- Support vector machine failure model
- Gradient boosting machine failure model
- Summary of findings

The Problem

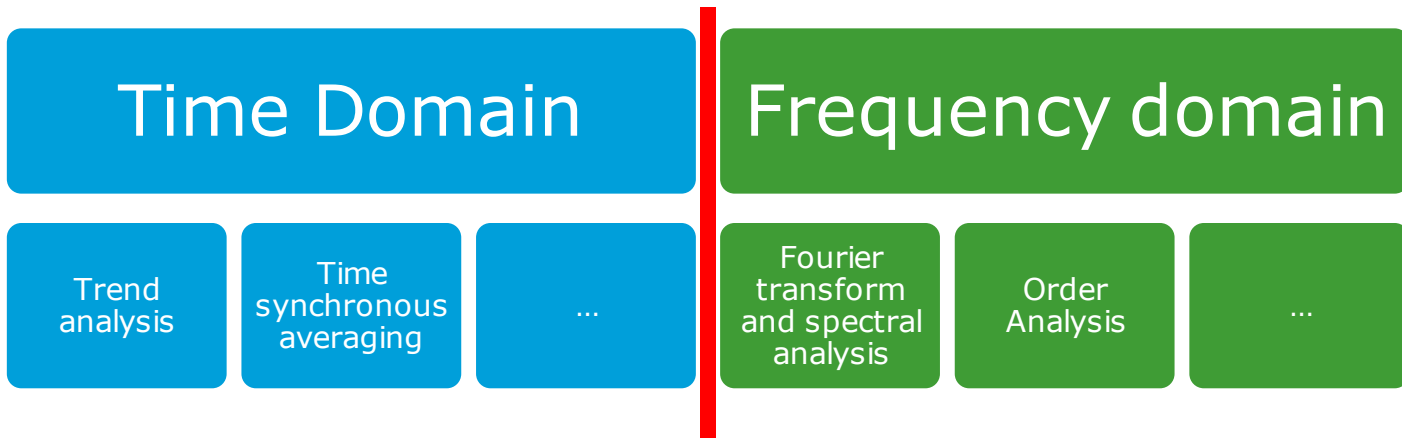
- Goal
 - Single model maximizing the use of high frequency ($f \geq 1$ Hz) available SCADA signals real-time accurate condition monitoring (CM) to detect and classify gear box faults
- Challenges
 - Multiple mechanical causes of gearbox deterioration
 - Increasing number of component configurations
 - Increasing number of sensor configurations
 - More high frequency sensor signals available



Ungraded

The Problem

Current Serial CM Analysis Methods



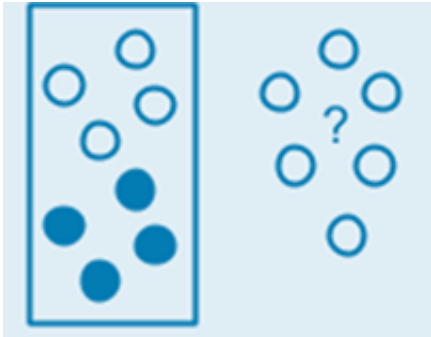
- Well established methodology and guidelines
- Capitalize on physical mechanism behind particular fault
- Multiple customized singular methods concurrently used
- Minimal use of hardware resources
- No dominate One-Size-Fits-All approach

Developments Around Data

- Big data is now just “Dysfunctional Data”
- Hardware constraints no longer a limiting factor
 - Sophisticated ontologies for relational databases in cloud computing
 - Distributed computing environments for alternative storage and processing
- Statistical tools now available
 - Development of fast parallel processing algorithms
 - Ensemble models now computationally feasible within standard software
- Collected wealth of data required for machine learning algorithms
 - Sufficient duration high quality data sets exist for pattern recognition
 - Synthesis of methods
 - Classification as well as detection possible

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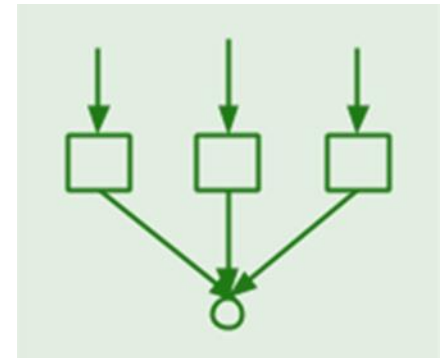
Machine Learning Ensemble Approaches



- Supervised Machine Learning
 - Excellent at anomaly detection in high dimensional spaces
 - Established results within conditional monitoring literature: artificial neural networks, self organizing maps, k-means clustering,...

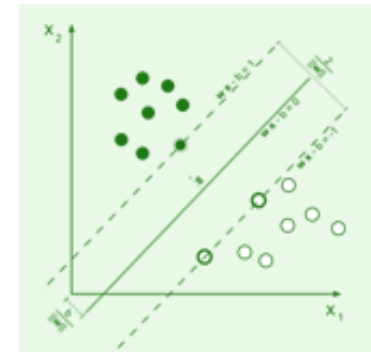
- Ensemble Methods

- Combine multiple weak models to create strong predictor
 - Support Vector Machines
 - Gradient Boosting Machines



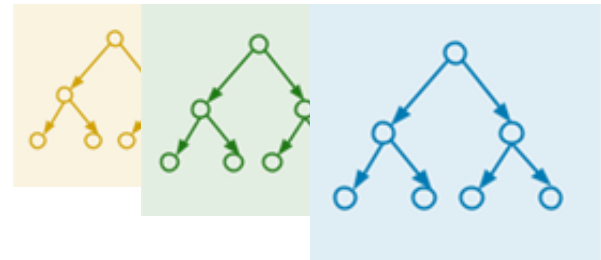
Support vector machine

- Support Vector Machine (SVM) is a non-probabilistic binary classifier which maps features into a separable space
 - Utilize a hyperplane with maximum margin to separate different classes of data
 - Can include non-linear features via kernel (RBF) trick
 - Hyperparameter tuning using grid search with k-fold cross validation
- Ensemble SVM method
 - Subsample the data run algorithm in parallel
 - Weight samples to compensate for unequal class sizes
 - Allow models vote on a prediction
- One Versus All multi-class model
 - Consecutively build many binary classifiers learned to identify only one distinct class



Gradient boosting machine

- Gradient boosting machine (GBM) adaptively combines weak classifier models to form a strong classifier model minimizing pseudo-residuals
 - Decision trees are the base-learner models
 - Boosting sequentially adds new weak learners based on a loss function optimizing instances misclassified by previous learner
 - Intrinsic feature selection
- Rare incident compensation
 - Additional weight vector for to the false positives error and false negatives added due to small incidents in singular classes
 - Weights are multiplied by the classification error at each iteration of the learning process

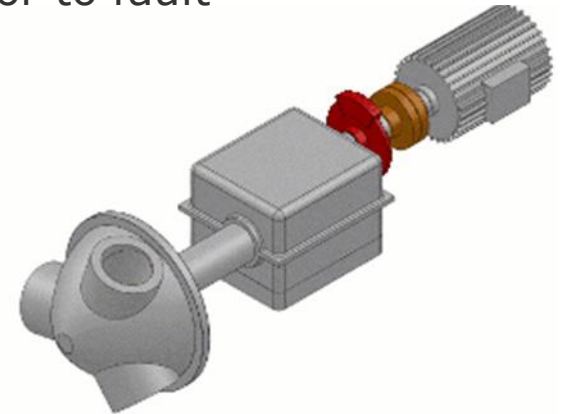


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The Data

speed	acceleration	power	electrical	temperature
<ul style="list-style-type: none">• generator RPM• wind• ...	<ul style="list-style-type: none">• rotor bearing• generator bearing• gear box• ...	<ul style="list-style-type: none">• turbine production• torque• ...	<ul style="list-style-type: none">• voltage phase• current phase• ...	<ul style="list-style-type: none">• nacelle• bearing• gear box• slip ring• generator• ambient• ...

- Three different gearbox fault types to classify = Four classes
- Minimum of Two-months clear operational data prior to fault for training set
- Four year total series
- Multiple instances of each fault
 - Includes simulated fault data of each type



SVM & GBM Model Building

Pre-process Data*

Training / Test / Validation Partition

Feature Creation*

Iterative Model Creation

Prediction Validations

Results Comparison

Classification Rate			
	Fault Type		
	Bearing Crack	Broken Gear tooth	Gear pitting
SVM	79%	76%	72%
GBM	92%	88%	84%

	Average Training Time (minutes)
SVM	14.22
GBM	38.19

	Average Prediction Time (seconds)
SVM	7.45
GBM	5.63

Closing Remarks

- Key Findings
 - Ensemble machine learning algorithms are a viable tool for condition monitoring mechanical fault detection applications utilizing many sensors with high frequency data
 - This study indicates ensemble Gradient Boosting Machines can outperform Support Vector Machines in multi-class gearbox fault classification

- Caveat Emptor
 - Missing values need to be handled with consideration
 - Domain expertise required
 - Model will not identify novel fault pattern
 - Dynamic
 - Models improve with additional fault library training, but grow
 - Retrain with the addition of new sensor signals

References

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Thank you for your attention

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